

Parametric estimation of exponential distribution in informative model of random censorship from both sides

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Introduction. In biomedical studies of individuals for survival, in engineering tests of technical devices for reliability, there may be cases when the tested objects coming under observation after a certain random time after the start of testing. This phenomenon is called delayed entry or left random censoring. The random variable (r.v.) X that characterizes the lifetime of the tested object becomes to observation under the condition $X \geq L$. Here L is the moment when the object was placed under observation. In addition to this, r.v. X may also be censored from the right by some other r.v. Y . We are interested in r.v. X which will be subjected to random censorship from both sides by random vector (L, Y) . Let r.v.-s L , X and Y are mutually independent with continuous distribution functions (d.f.) K , F and G respectively.

1. Informative model of random censorship from both sides. Let $\{(X_k, L_k, Y_k), k \geq 1\}$ be a sequence of independent realizations of the triple (X, L, Y) and

$$S^{(n)} = \{(Z_i, \Delta_i), i = 1, \dots, n\}$$

-the observed sample, where $Z_i = \max\{L_i, \min\{X_i, Y_i\}\}$, $\Delta_i = (\delta_i^{(0)}, \delta_i^{(1)}, \delta_i^{(2)})$, with $\delta_i^{(0)} = I(\min(X_i, Y_i) < L_i)$, $\delta_i^{(1)} = I(L_i \leq X_i < Y_i)$, $\delta_i^{(2)} = I(L_i \leq Y_i < X_i)$ and $I(A)$ standing for indicator of the event A . Note that in sample $S^{(n)}$ the number of observed r.v.-s X_i is equal to $\delta_1^{(1)} + \dots + \delta_n^{(1)}$. The statistical task is consist in estimating of d.f. F from a sample $S^{(n)}$. However, such a general statement of the estimating problem, d.f.-s K and G are considered as a nuisance. In this paper, we will investigate the evaluation of d.f. F in the case of informative censoring from two sources, when d.f.-s K and G functionally depend on F . To describe such a model by H and N we denote d.f.-s of r.v.-s Z_i and $V_i = \min(X_i, Y_i)$. Then it is easy to see, that

$$H(x) = K(x)N(x), \quad N(x) = 1 - (1 - F(x))(1 - G(x)), \quad x \in \mathbb{R}^1. \quad (1)$$

Assume that there are positive unknown parameters θ, β such that following representations are valid for all $x \in \mathbb{R}^1$:

$$\begin{cases} 1 - G(x) = (1 - F(x))^\theta, \\ K(x) = (N(x))^\beta, \end{cases} \quad (2)$$

where the parameter β is responsible for the power of censoring from the left, and θ -from the right. In this model, the censoring parameters θ and β , which determine the deepness of censorship from both sides. From formulas (1) and (2), it is not difficult to derive the following representation for d.f. F :

$$1 - F(x) = \left[1 - (H(x))^\lambda\right]^\gamma, \quad x \in \mathbb{R}^1, \quad (3)$$

where $\lambda = \frac{1}{1+\beta}$, $\gamma = \frac{1}{1+\theta}$ and therefore, the closeness of the parameters λ and γ to 1, denotes the weakness of the censoring. Using representation (3), we can construct a semiparametric estimate for F over a sample $S^{(n)}$ by estimating a triple $(H(x), \lambda, \gamma)$:

$$F_n(x) = 1 - \left[1 - (H_n(x))^{\lambda_n}\right]^{\gamma_n}, \quad x \in \mathbb{R}^1. \quad (4)$$

2. Parametric estimation of exponential distribution. Now let's look at the case in model (2) $X_i \sim F(x, \alpha) = 1 - e^{-\frac{x}{\alpha}}$, $x \geq 0$, $\alpha > 0$, $Y_i \sim G(x, \alpha) = 1 - (1 - F(x, \alpha))^\theta$, $\theta > 0$ and $L_i \sim K(x, \alpha) = (N(x, \alpha))^\beta$, $\beta > 0$. Then in accordance with (3) we have $1 - e^{-\frac{x}{\alpha}} = 1 - \left[1 - (H(x))^\lambda\right]^\gamma$ and we get for $H(x)$ the expression $H(x) = \left(1 - e^{-\frac{x}{\alpha \cdot \gamma}}\right)^{\frac{1}{\lambda}}$. Differentiate this distribution over by x we have density of $H(x)$ as $h(x) = \frac{1}{\alpha \lambda \gamma} e^{-\frac{x}{\alpha \gamma}} \left(1 - e^{-\frac{x}{\alpha \gamma}}\right)^{\frac{1-\lambda}{\lambda}}$. Now we construct a maximum likelihood function for $h(x)$ using the sample from Z_i :

$$\begin{aligned} L(Z, \alpha) &= \ln \left((\alpha \lambda \gamma)^{-n} \cdot e^{-\frac{\sum_{i=1}^n Z_i}{\alpha \gamma}} \left(\left(1 - e^{-\frac{Z_1}{\alpha \gamma}}\right) \left(1 - e^{-\frac{Z_1}{\alpha \gamma}}\right) \times \dots \times \right. \right. \\ &\quad \left. \left. \times \left(1 - e^{-\frac{Z_n}{\alpha \gamma}}\right) \right)^{\frac{1-\lambda}{\lambda}} \right) = -n \ln(\alpha \lambda \gamma) - \frac{\sum_{i=1}^n Z_i}{\alpha \gamma} + \frac{1-\lambda}{\lambda} \sum_{i=1}^n \ln \left(1 - e^{-\frac{Z_i}{\alpha \gamma}}\right). \end{aligned}$$

Now calculate $\frac{\partial L(Z, \alpha)}{\partial \alpha}$:

$$\frac{\partial L(Z, \alpha)}{\partial \alpha} = -\frac{n}{\alpha} + \frac{\sum_{i=1}^n Z_i}{\alpha^2 \gamma} + \frac{1-\lambda}{\lambda} \sum_{i=1}^n \frac{-\frac{Z_i}{\alpha^2 \gamma} e^{-\frac{Z_i}{\alpha \gamma}}}{1 - e^{-\frac{Z_i}{\alpha \gamma}}}.$$

We solve maximum likelihood equation $\frac{\partial L(Z, \alpha)}{\partial \alpha} = 0$ by α and get

$$\alpha = \frac{1}{\lambda \gamma n} \cdot \sum_{i=1}^n Z_i \cdot \left(1 - \frac{1-\lambda}{(H(Z_i))^\lambda}\right). \quad (5)$$

From (5), instead of (H, λ, γ) of supplying appropriate estimates $(H_n, \lambda_n, \gamma_n)$, we obtain an semiparametric estimate for the parameter α :

$$\alpha_n = \frac{1}{\lambda_n \gamma_n n} \cdot \sum_{i=1}^n Z_i \cdot \left(1 - \frac{1-\lambda_n}{(H_n(Z_i))^{\lambda_n}}\right). \quad (6)$$

From (6), we obtain an estimate $F(x, \alpha_n)$ for $F(x, \alpha)$. Now we draw the following graphs using numerical methods, in order to compare the above estimate (4) and estimate constructed using (5). In conclusion, we can say that the estimate $F(x, \alpha_n)$ would be very good (Figures 1-4).

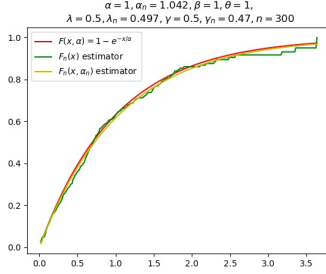


Figure 1: $\beta = 1$, $\theta = 1$, $n = 300$

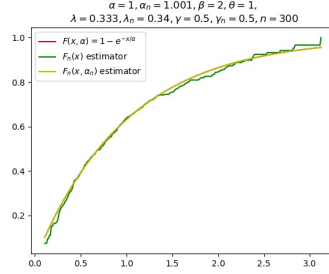


Figure 2: $\beta = 2$, $\theta = 1$, $n = 300$

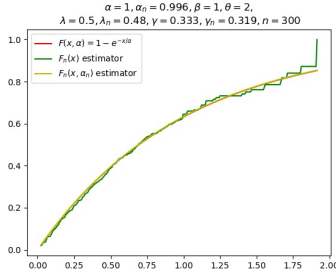


Figure 3: $\beta = 1$, $\theta = 2$, $n = 300$

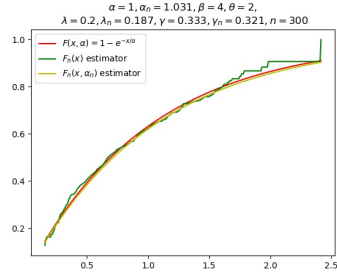


Figure 4: $\beta = 4$, $\theta = 2$, $n = 300$

References

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